

Machine-Level Programming IV:

Data

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Today

■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

■ Structures

- Allocation
- Access
- Alignment

■ Floating Point

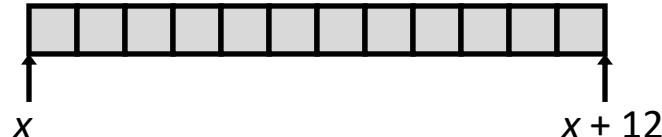
Array Allocation

■ Basic Principle

$T \mathbf{A}[L];$

- Array of data type T and length L
- Contiguously allocated region of $L * \text{sizeof}(T)$ bytes in memory

```
char string[12];
```



```
int val[5];
```



```
double a[3];
```



```
char *p[3];
```

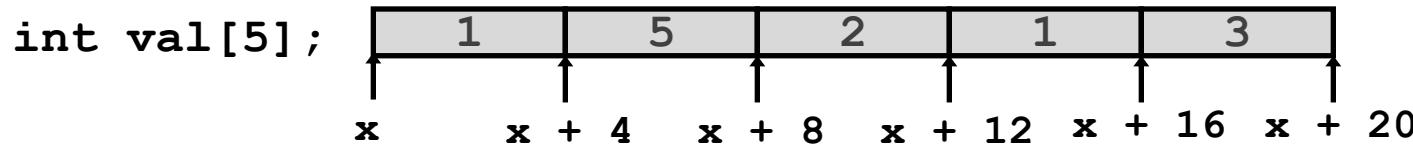


Array Access

■ Basic Principle

$T \mathbf{A}[L]$;

- Array of data type T and length L
- Identifier \mathbf{A} can be used as a pointer to array element 0: Type T^*



■ Reference Type Value

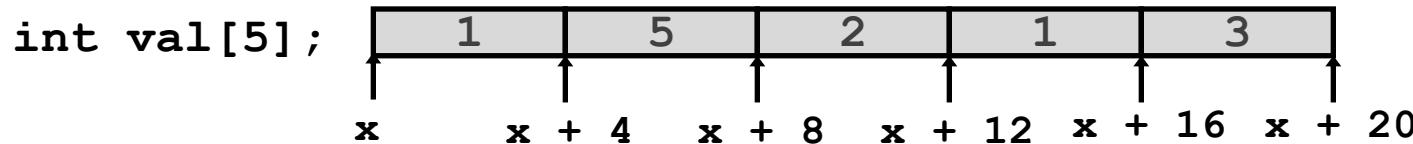
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	
<code>val+1</code>	<code>int *</code>	
<code>&val[2]</code>	<code>int *</code>	
<code>val[5]</code>	<code>int</code>	
<code>*(val+1)</code>	<code>int</code>	
<code>val + i</code>	<code>int *</code>	

Array Access

■ Basic Principle

$T \mathbf{A}[L]$;

- Array of data type T and length L
- Identifier \mathbf{A} can be used as a pointer to array element 0: Type T^*



■ Reference Type Value

<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	<code>x</code>
<code>val+1</code>	<code>int *</code>	<code>x + 4</code>
<code>&val[2]</code>	<code>int *</code>	<code>x + 8</code>
<code>val[5]</code>	<code>int</code>	??
<code>*(val+1)</code>	<code>int</code>	5 // <code>val[1]</code>
<code>val + i</code>	<code>int *</code>	<code>x + 4 * i</code> // <code>&val[i]</code>

Quiz Time!

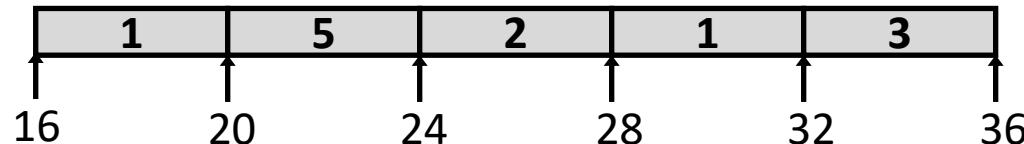
Exercise 3.36

Array Example

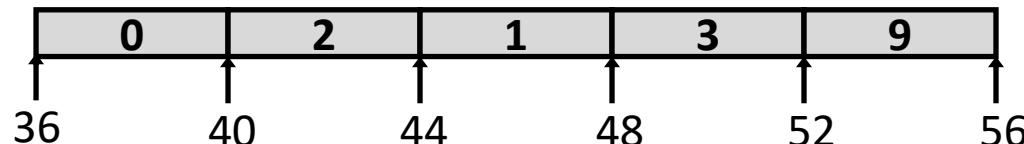
```
#define ZLEN 5  
typedef int zip_dig[ZLEN];
```

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

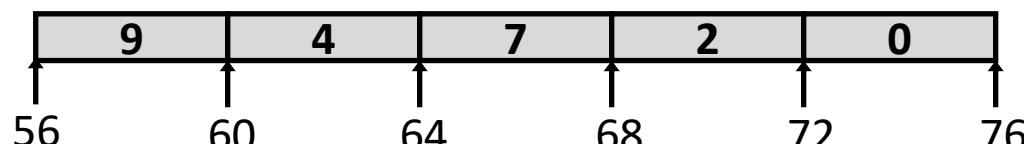
`zip_dig cmu;`



`zip_dig mit;`



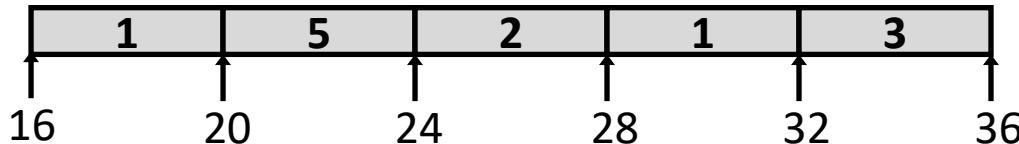
`zip_dig ucb;`



- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in **successive 20 byte blocks**
 - Not guaranteed to happen in general

Array Accessing Example

```
zip_dig cmu;
```



```
int get_digit
    (zip_dig z, int digit)
{
    return z[digit];
}
```

x86-64

```
# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register **%rdi** contains starting address of array
- Register **%rsi** contains array index
- Desired digit at **%rdi + 4*%rsi**
- Use memory reference **(%rdi,%rsi,4)**

Array Loop Example

```
void zincr(zip_dig z) {
    size_t i;
    for (i = 0; i < ZLEN; i++)
        z[i]++;
}
```

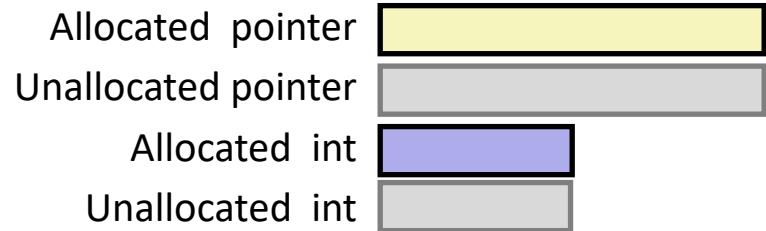
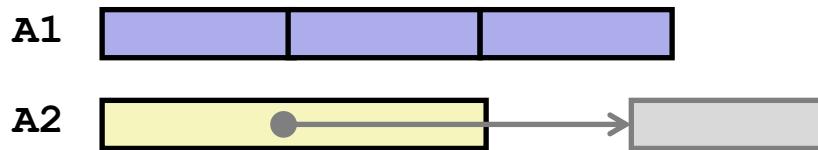
```
# %rdi = z
movl    $0, %eax
jmp     .L3
.L4:
    addl    $1, (%rdi,%rax,4)
    addq    $1, %rax
.L3:
    cmpq    $4, %rax
    jbe     .L4
rep; ret
```

Quiz Time!

Exercise 3.37

Understanding Pointers & Arrays #1

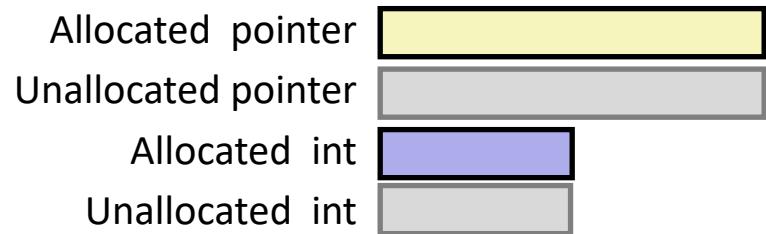
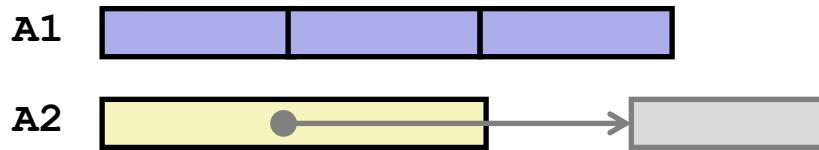
Decl	A1 , A2			*A1 , *A2		
	Comp	Bad	Size	Comp	Bad	Size
int A1[3]						
int *A2						



- **Comp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by sizeof**

Understanding Pointers & Arrays #1

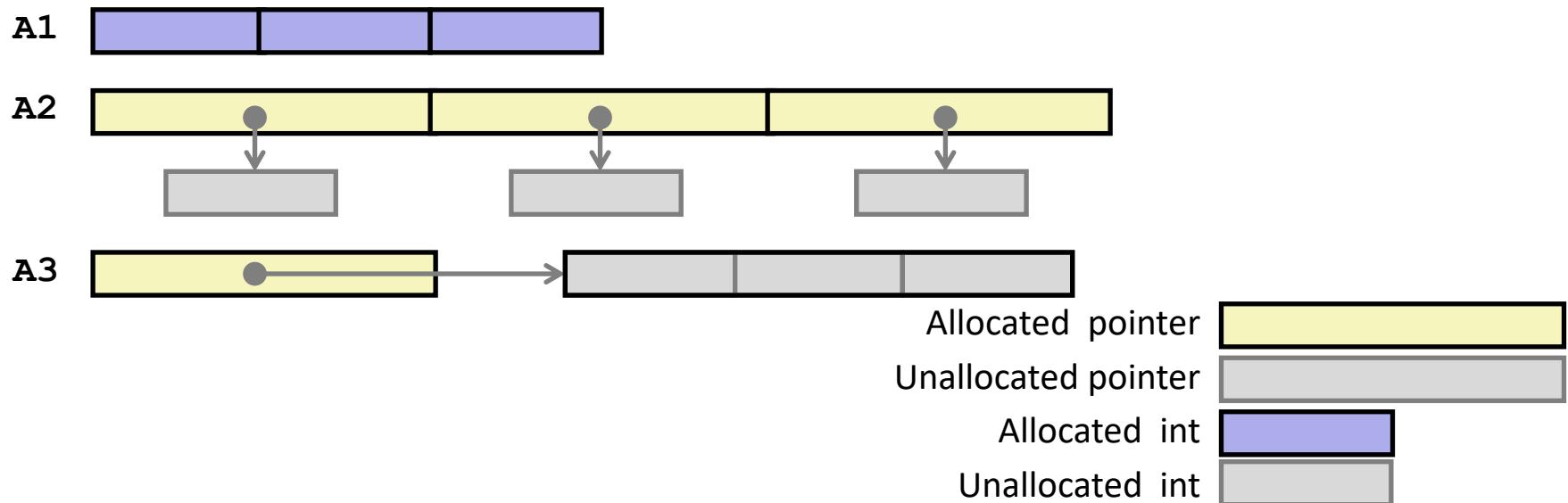
Decl	A1 , A2			*A1 , *A2		
	Comp	Bad	Size	Comp	Bad	Size
int A1[3]	Y	N	12	Y	N	4
int *A2	Y	N	8	Y	Y	4



- **Comp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by sizeof**

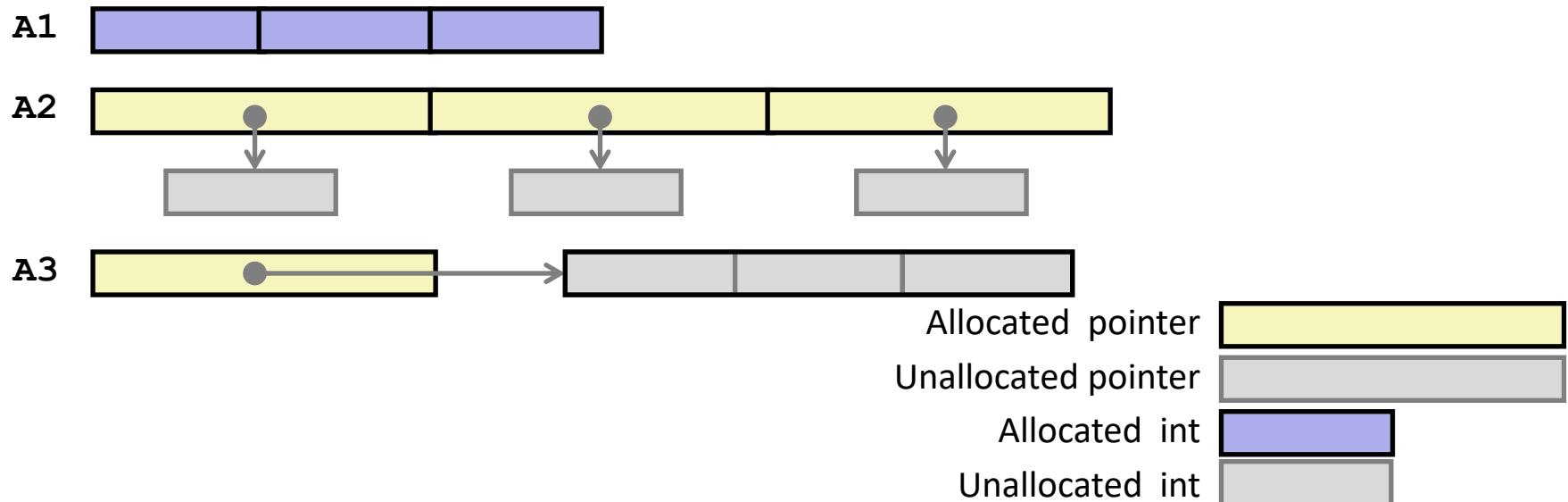
Understanding Pointers & Arrays #2

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>									
<code>int *A2[3]</code>									
<code>int (*A3)[3]</code>									



Understanding Pointers & Arrays #2

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>	Y	N	12	Y	N	4	N	-	-
<code>int *A2[3]</code>	Y	N	24	Y	N	8	Y	Y	4
<code>int (*A3)[3]</code>	Y	N	8	Y	Y	12	Y	Y	4



Multidimensional (Nested) Arrays

■ Declaration

$T \ A[R][C];$

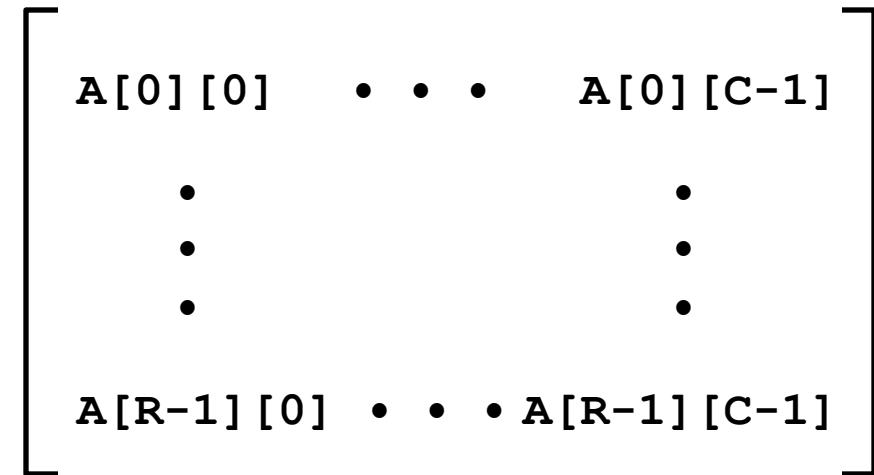
- 2D array of data type T
- R rows, C columns

■ Array Size

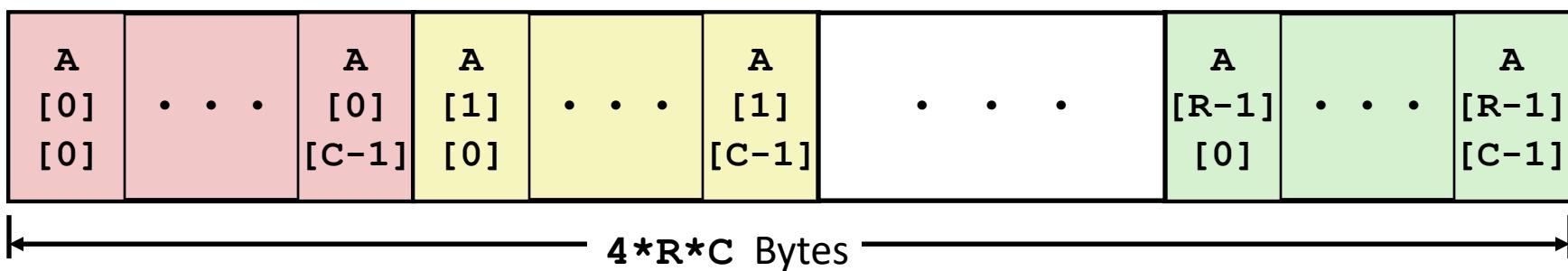
- $R * C * \text{sizeof}(T)$ bytes

■ Arrangement

- Row-Major Ordering



```
int A[R][C];
```

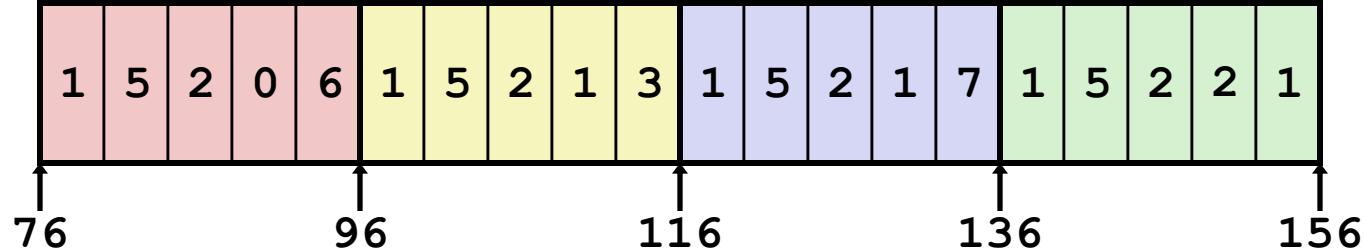


Nested Array Example

```
#define PCOUNT 4
typedef int zip_dig[5];

zip_dig pgh[PCOUNT] =
{{1, 5, 2, 0, 6},
 {1, 5, 2, 1, 3 },
 {1, 5, 2, 1, 7 },
 {1, 5, 2, 2, 1 }};
```

zip_dig
pgh[4];



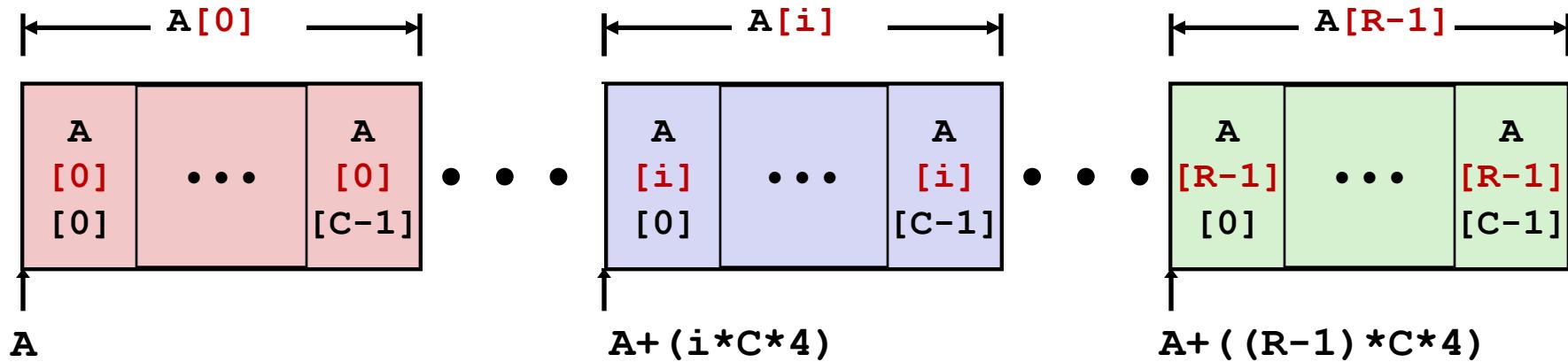
- “`zip_dig pgh [4]`” equivalent to “`int pgh [4] [5]`”
 - Variable `pgh`: array of 4 elements, allocated contiguously
 - Each element is an array of 5 `int`'s, allocated contiguously
- “Row-Major” ordering of all elements in memory

Nested Array Row Access

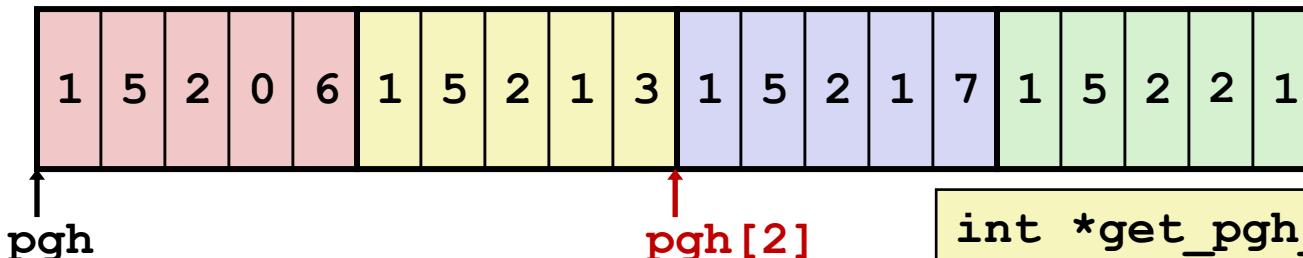
■ Row Vectors

- $\mathbf{A[i]}$ is array of C elements of type T
- Starting address $\mathbf{A} + \mathbf{i} * (\mathbf{C} * \text{sizeof}(T))$

```
int A[R][C];
```



Nested Array Row Access Code



```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

```
# %rdi = index
    leaq (%rdi,%rdi,4),%rax # 5 * index
    leaq pgh(,%rax,4),%rax  # pgh + (20 * index)
```

■ Row Vector

- `pgh[index]` is array of 5 int's
- Starting address `pgh+20*index`

■ Machine Code

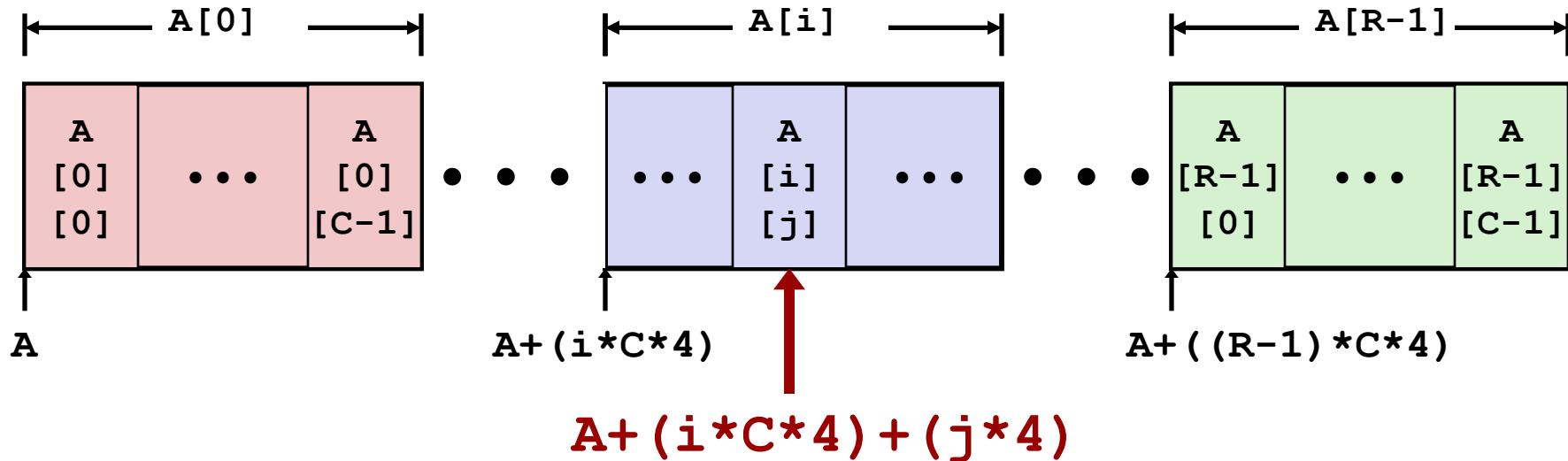
- Computes and returns address
- Compute as `pgh + 4*(index+4*index)`

Nested Array Element Access

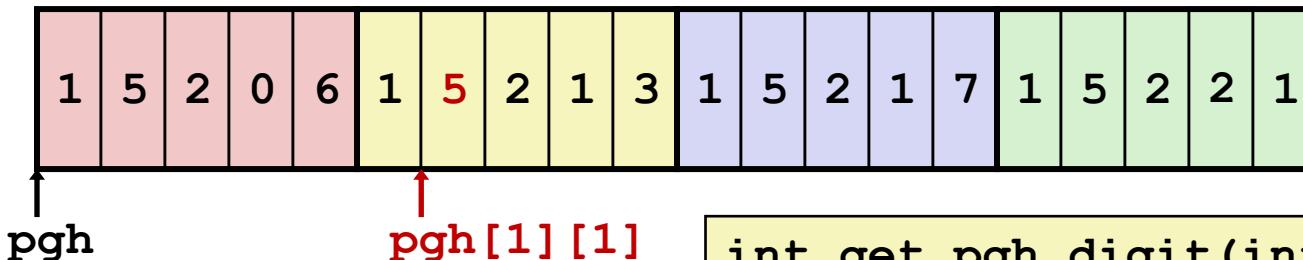
■ Array Elements

- $A[i][j]$ is element of type T , which requires K bytes
- Address $A + i * (C * K) + j * K$
 $= A + (i * C + j) * K$

```
int A[R][C];
```



Nested Array Element Access Code



```
int get_pgh_digit(int index, int dig)
{
    return pgh[index][dig];
}
```

```
leaq (%rdi,%rdi,4), %rax      # 5*index
addq %rax, %rsi                # 5*index+dig
movl pgh(,%rsi,4), %eax       # M[pgh + 4*(5*index+dig)]
```

■ Array Elements

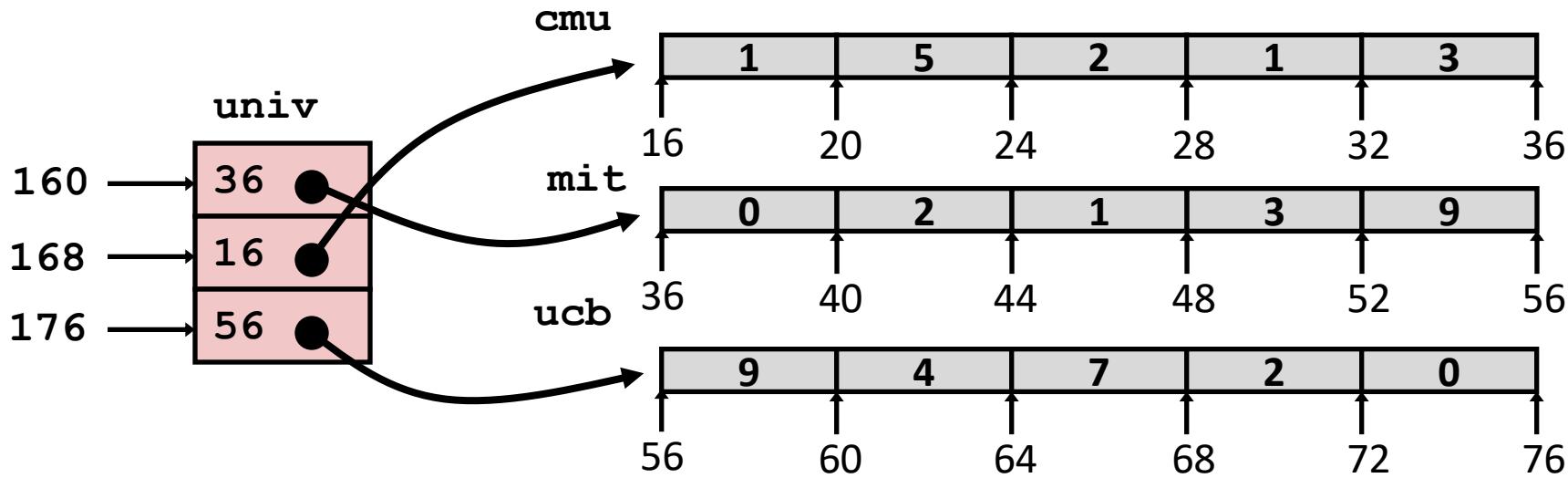
- `pgh[index][dig]` is `int`
- Address: $pgh + 20*index + 4*dig$
= $pgh + 4*(5*index + dig)$

Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

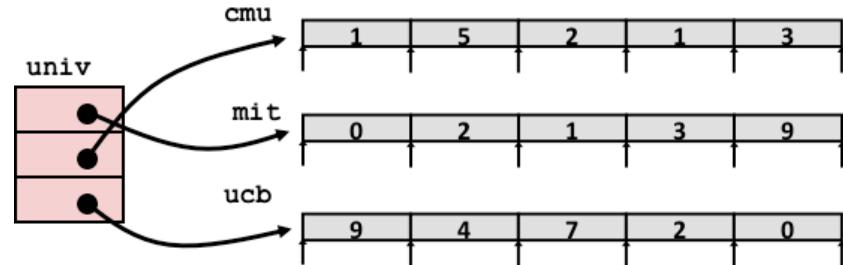
```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, ucb};
```

- Variable **univ** denotes array of 3 elements
- Each element is a pointer
 - 8 bytes
- Each pointer points to array of int's



Element Access in Multi-Level Array

```
int get_univ_digit  
    (size_t index, size_t digit)  
{  
    return univ[index][digit];  
}
```



```
salq    $2, %rsi          # 4*digit  
addq    univ(,%rdi,8), %rsi # p = univ[8*index] + 4*digit  
movl    (%rsi), %eax       # return *p  
ret
```

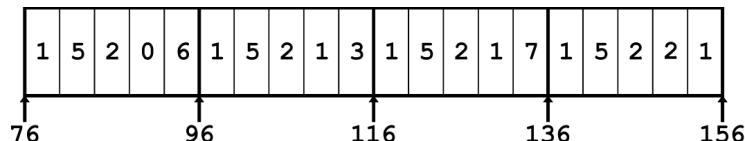
■ Computation

- Element access **Mem[Mem[univ+8*index]+4*digit]**
- Must do two memory reads
 - First get pointer to row array
 - Then access element within array

Array Element Accesses

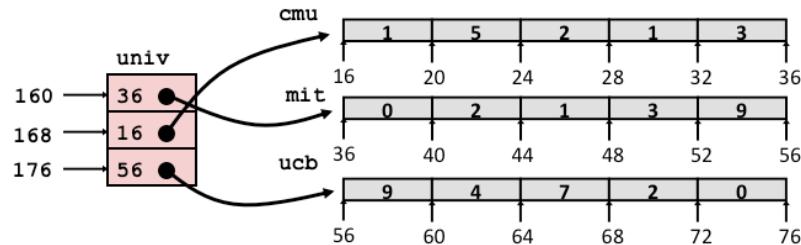
Nested array

```
int get_pgh_digit  
  (size_t index, size_t digit)  
{  
    return pgh[index] [digit];  
}
```



Multi-level array

```
int get_univ_digit  
  (size_t index, size_t digit)  
{  
    return univ[index] [digit];  
}
```



Accesses looks **similar** in C, but address **computations** very different:

`Mem[pgh+20*index+4*digit]`

`Mem[Mem[univ+8*index]+4*digit]`

$N \times N$ Matrix Code

■ Fixed dimensions

- Know value of N at compile time

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element A[i][j] */
int fix_ele(fix_matrix A,
            size_t i, size_t j)
{
    return A[i][j];
}
```

■ Variable dimensions, explicit indexing

- Traditional way to implement dynamic arrays

```
#define IDX(n, i, j) ((i)*(n)+(j))
/* Get element A[i][j] */
int vec_ele(size_t n, int *A,
            size_t i, size_t j)
{
    return A[IDX(n,i,j)];
}
```

■ Variable dimensions, implicit indexing

- Now supported by gcc

```
/* Get element A[i][j] */
int var_ele(size_t n, int A[n][n],
            size_t i, size_t j) {
    return A[i][j];
}
```

$N \times N$ Matrix

Code

```
7 int abc(int n, int a[n][n], int i, int j) {
8     printf("%d, %d: %d\n", i, j, a[i][j]);
9 }
10 int main() {
11     int i, j=1;
12
13     int a[2][8] = {{1,2,3,4,5,6,7,8},
14                   {11,12,13,14,15,16,17,18}};
15     abc(4, a, 1, 1);
16
17 }
```

1, 1, 6

```
7 int abc(int n, int m, int a[n][m], int i, int j) {
8     printf("%d, %d: %d\n", i, j, a[i][j]);
9 }
10 int main() {
11     int i, j=1;
12
13     int a[2][8] = {{1,2,3,4,5,6,7,8},
14                   {11,12,13,14,15,16,17,18}};
15     abc(8, 2, a, 1, 1);
16
17 }
```

1, 1, 4

16 X 16 Matrix Access

■ Array Elements

- `int A[16][16];`
- Address `A + i * (C * K) + j * K`
- $C = 16, K = 4$

```
/* Get element A[i][j] */  
int fix_ele(fix_matrix A, size_t i, size_t j) {  
    return A[i][j];  
}
```

```
# A in %rdi, i in %rsi, j in %rdx  
salq    $6, %rsi          # 64*i  
addq    %rsi, %rdi         # A + 64*i  
movl    (%rdi,%rdx,4), %eax # Mem[A + 64*i + 4*j]  
ret
```

$n \times n$ Matrix Access

■ Array Elements

- `size_t n;`
- `int A[n][n];`
- Address `A + i * (C * K) + j * K`
- $C = n, K = 4$
- Must perform integer multiplication

```
/* Get element A[i][j] */
int var_ele(size_t n, int A[n][n], size_t i, size_t j)
{
    return A[i][j];
}
```

```
# n in %rdi, A in %rsi, i in %rdx, j in %rcx
imulq    %rdx, %rdi          # n*i
leaq     (%rsi,%rdi,4), %rax # A + 4*n*i
movl     (%rax,%rcx,4), %eax # A + 4*n*i + 4*j
ret
```

Example: Array Access

```
#include <stdio.h>

#define ZLEN 5
#define PCOUNT 4
typedef int zip_dig[ZLEN];

int main(int argc, char** argv) {
    zip_dig pgm =
        {{1, 5, 2, 0, 6},
         {1, 5, 2, 1, 3 },
         {1, 5, 2, 1, 7 },
         {1, 5, 2, 2, 1 }};
    int *linear_zip = (int *) pgm;
    int *zip2 = (int *) pgm[2];
    int result =
        pgm[0][0] +
        linear_zip[7] +
        *(linear_zip + 8) +
        zip2[1];
    printf("result: %d\n", result);
    return 0;
}
```

```
linux> ./array
result: 9
```

Example: Array Access

```
#include <stdio.h>

#define ZLEN 5
#define PCOUNT 4
typedef int zip_dig[ZLEN];

int main(int argc, char** argv) {
    zip_dig pgm[PCOUNT] =
        {{1, 5, 2, 0, 6},
         {1, 5, 2, 1, 3 },
         {1, 5, 2, 1, 7 },
         {1, 5, 2, 2, 1 }};
    int *linear_zip = (int *) pgm;
    int *zip2 = (int *) pgm[2];
    int result =
        pgm[0][0] +
        linear_zip[7] +
        *(linear_zip + 8) +
        zip2[1];
    printf("result: %d\n", result);
    return 0;
}
```

```
linux> ./array
result: 9
```

Today

■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

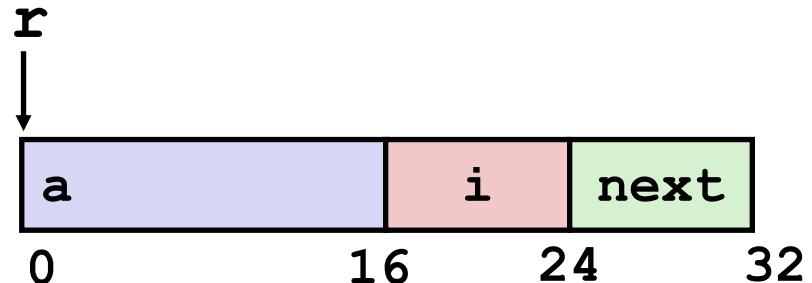
■ Structures

- Allocation
- Access
- Alignment

■ Floating Point

Structure Representation

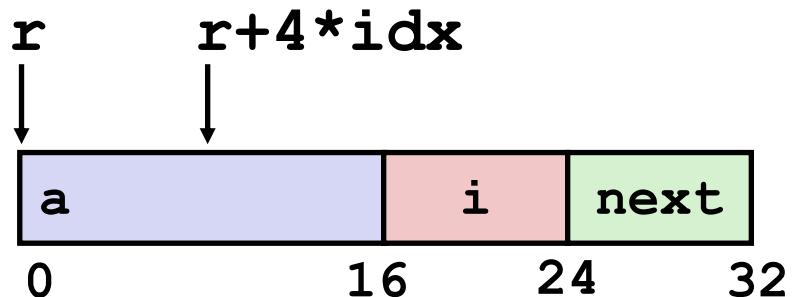
```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



- Structure represented as **block of memory**
 - Big enough to hold all of the fields
- Fields ordered according to declaration
 - Even if another ordering could yield a more compact representation
- **Compiler** determines overall **size + positions of fields**
 - Machine-level program has no understanding of the structures in the source code

Generating Pointer to Structure Member

```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



■ Generating Pointer to Array Element

- Offset of each structure member determined at compile time
- Compute as `r + 4*idx`

```
int *get_ap  
(struct rec *r, size_t idx)  
{  
    return &(r->a[idx]);  
} // assembly code?
```

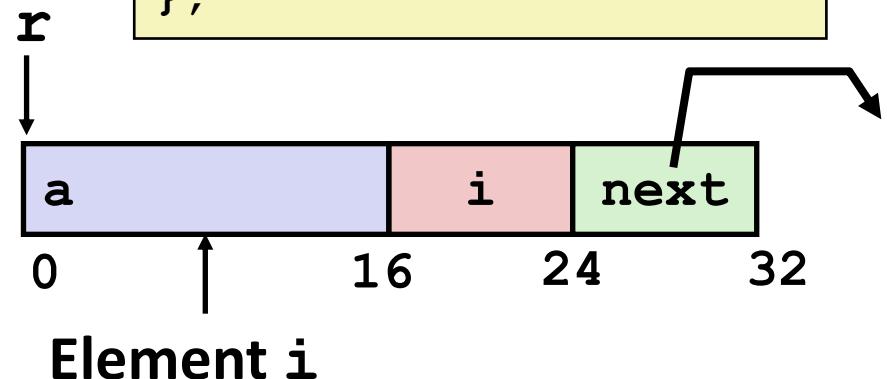
```
# r in %rdi, idx in %rsi  
leaq (%rdi,%rsi,4), %rax  
ret
```

Following Linked List

■ C Code

```
void set_val
    (struct rec *r, int val)
{
    while (r) {
        int i = r->i;
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



Register	Value
%rdi	r
%rsi	val

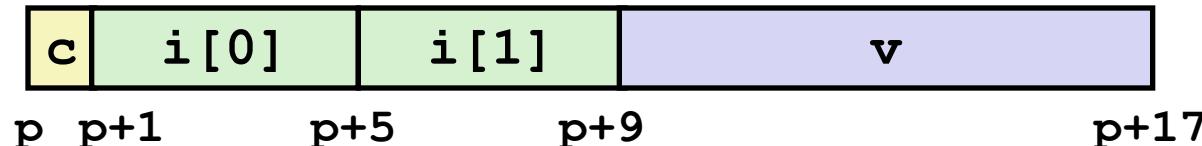
```
.L11:                                # loop:
    movslq  16(%rdi), %rax          #   i = Mem[r+16]
    movl    %esi, (%rdi,%rax,4)    #   Mem[r+4*i] = val
    movq    24(%rdi), %rdi         #   r = Mem[r+24]
    testq   %rdi, %rdi            #   Test r
    jne     .L11                  #   if !=0 goto loop
```

Quiz Time!

Exercise 3.41

Structures & Alignment

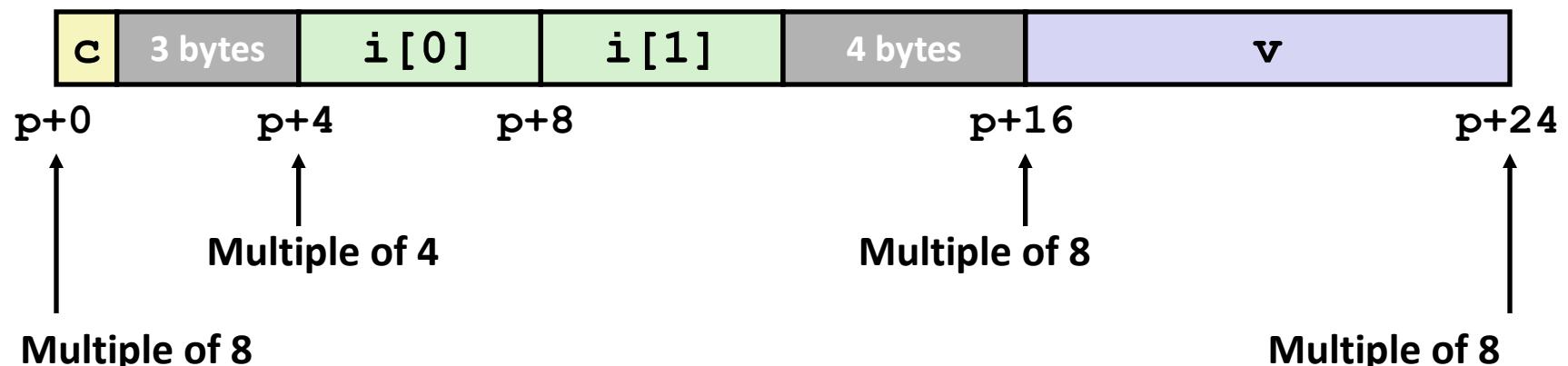
■ Unaligned Data



```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

■ Aligned Data

- Primitive data type requires **B** bytes implies
Address must be **multiple of B**



Alignment Principles

■ Aligned Data

- Primitive data type requires B bytes
- Address must be multiple of B
- Required on some machines; advised on x86-64

■ Motivation for Aligning Data

- Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
 - Inefficient to load or store datum that spans cache lines (64 bytes). Intel states should avoid crossing 16 byte boundaries.

[Cache lines will be discussed in Lecture 11.]

- Virtual memory trickier when datum spans 2 pages (4 KB pages)

[Virtual memory pages will be discussed in Lecture 17.]

■ Compiler

- Inserts gaps in structure to ensure correct alignment of fields

Specific Cases of Alignment (x86-64)

- **1 byte: `char`, ...**
 - no restrictions on address
- **2 bytes: `short`, ...**
 - lowest 1 bit of address must be 0_2
- **4 bytes: `int`, `float`, ...**
 - lowest 2 bits of address must be 00_2
- **8 bytes: `double`, `long`, `char *`, ...**
 - lowest 3 bits of address must be 000_2

Satisfying Alignment with Structures

■ Within structure:

- Must satisfy each element's alignment requirement

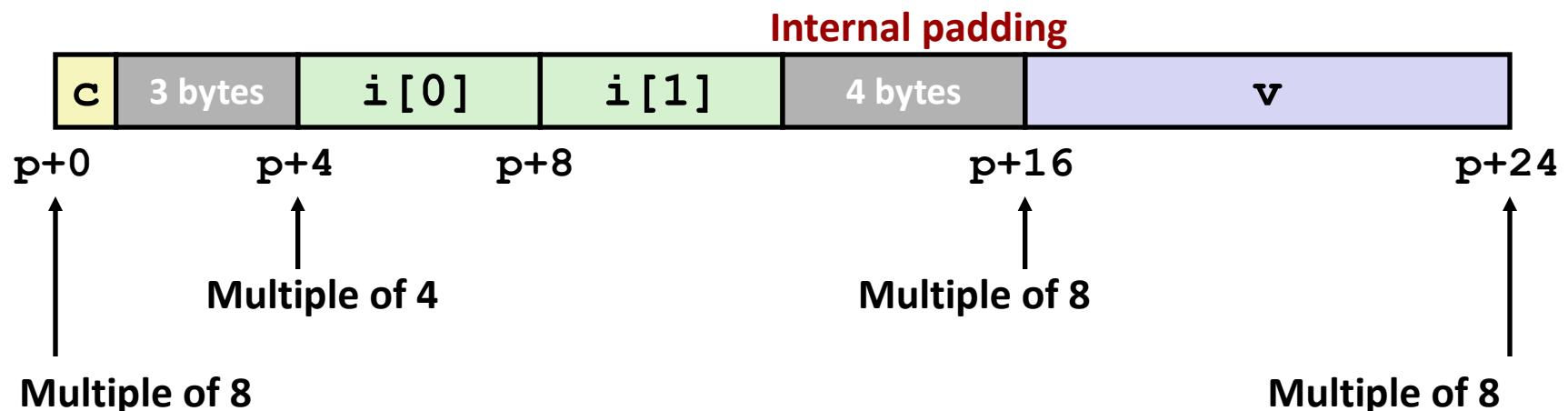
■ Overall structure placement

- Each structure has alignment requirement K
 - $K = \text{Largest alignment of any element}$
- Initial address & structure length must be multiples of K

■ Example:

- $K = 8$, due to **double** element

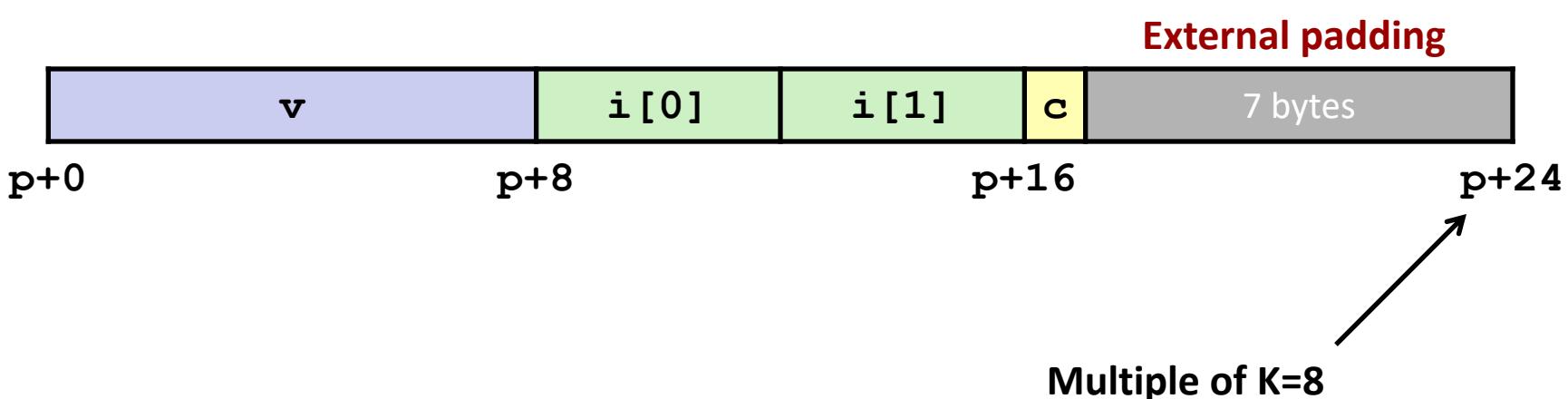
```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```



Meeting Overall Alignment Requirement

- For largest alignment requirement K
- Overall structure must be multiple of K

```
struct s2 {  
    double v;  
    int i[2];  
    char c;  
} *p;
```



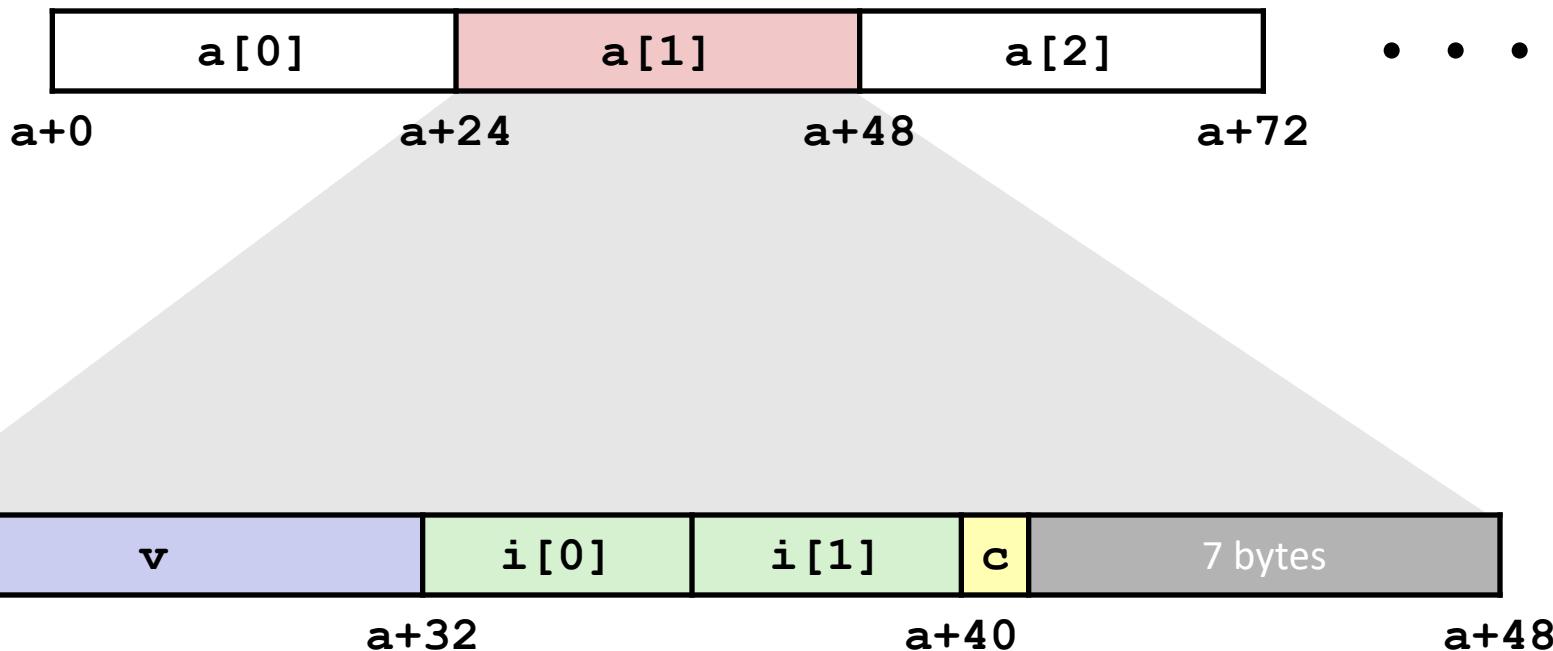
Quiz Time!

Exercise (3.44), 3.45

Arrays of Structures

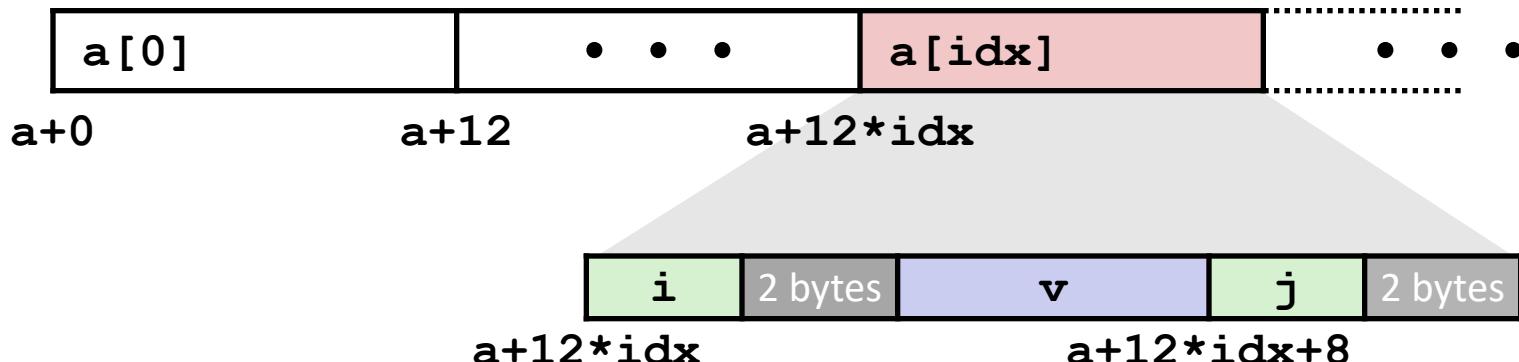
- Overall structure length multiple of K
- Satisfy alignment requirement for every element

```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} a[10];
```



Accessing Array Elements

- Compute array offset $12 * \text{idx}$
 - `sizeof(S3)`, including alignment spacers
- Element `j` is at offset 8 within structure
- Assembler gives offset `a+8`
 - Resolved during linking



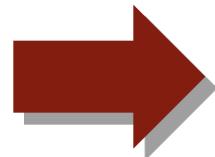
```
short get_j(int idx)  
{  
    return a[idx].j;  
}
```

```
# %rdi = idx  
leaq (%rdi,%rdi,2),%rax # 3*idx  
movzwl a+8(%rax,4),%eax
```

Saving Space

- Put large data types first

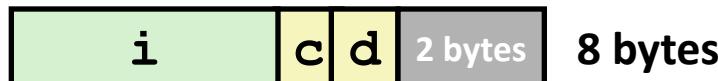
```
struct S4 {  
    char c;  
    int i;  
    char d;  
} *p;
```



```
struct S5 {  
    int i;  
    char c;  
    char d;  
} *p;
```



- Effect (largest alignment requirement K=4)



Example Struct Exam Question

Struct alignment. Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

1. Show how `foo` would be allocated in memory on an x86-64 Linux system. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.

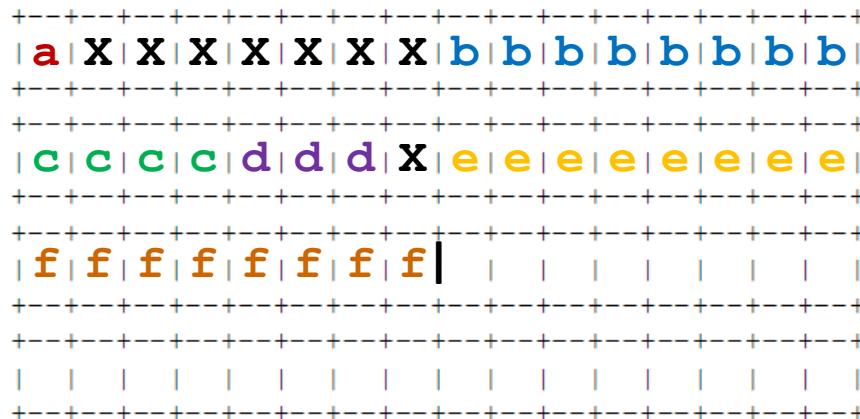


Example Struct Exam Question

Struct alignment. Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

1. Show how `foo` would be allocated in memory on an x86-64 Linux system. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.



Example Struct Exam Question (Cont'd)

Struct alignment. Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

2. Rearrange the elements of `foo` to conserve the most space in memory. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.

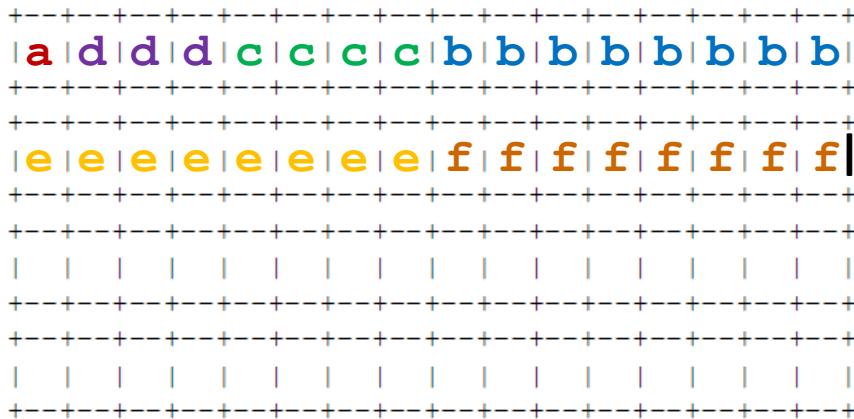


Example Struct Exam Question (Cont'd)

Struct alignment. Consider the following C struct declaration:

```
typedef struct {  
    char a;  
    long b;  
    float c;  
    char d[3];  
    int *e;  
    short *f;  
} foo;
```

2. Rearrange the elements of `foo` to conserve the most space in memory. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.



Today

■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

■ Structures

- Allocation
- Access
- Alignment

■ Floating Point

Background

■ History

- x87 FP
 - Legacy, very ugly
- SSE FP
 - Special case use of vector instructions
- AVX FP
 - Newest version
 - Similar to SSE (but registers are 32 bytes instead of 16)
 - Documented in book

Programming with SSE3

XMM Registers

- 16 total, each 16 bytes
- 16 single-byte integers



- 8 16-bit integers



- 4 32-bit integers



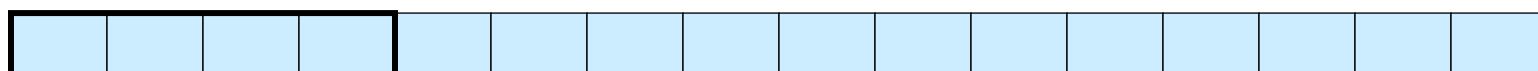
- 4 single-precision floats



- 2 double-precision floats



- 1 single-precision float

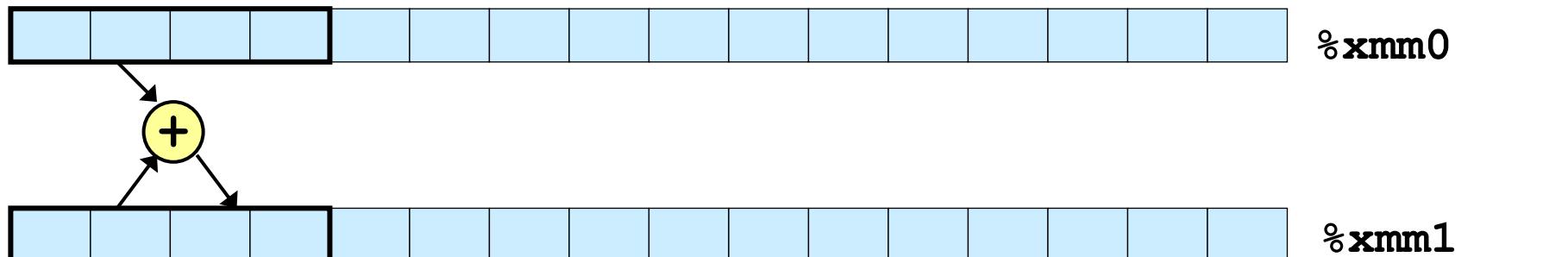


- 1 double-precision float

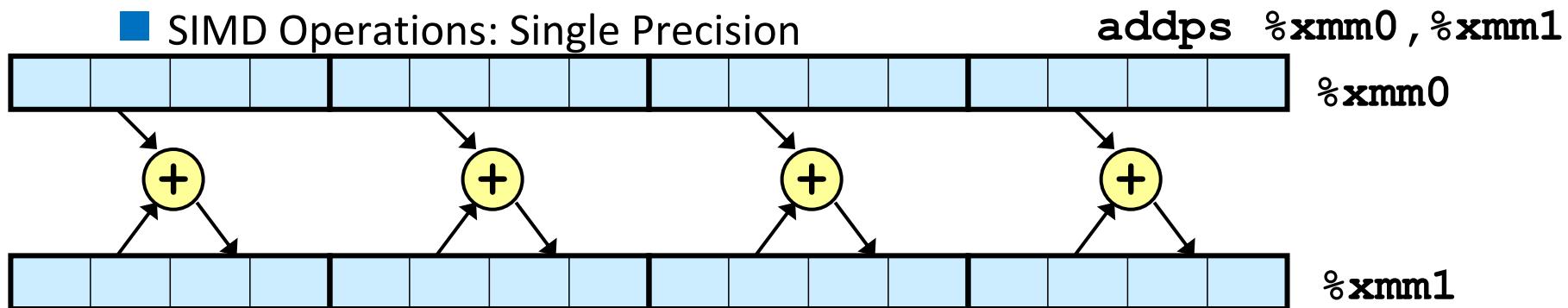


Scalar & SIMD Operations

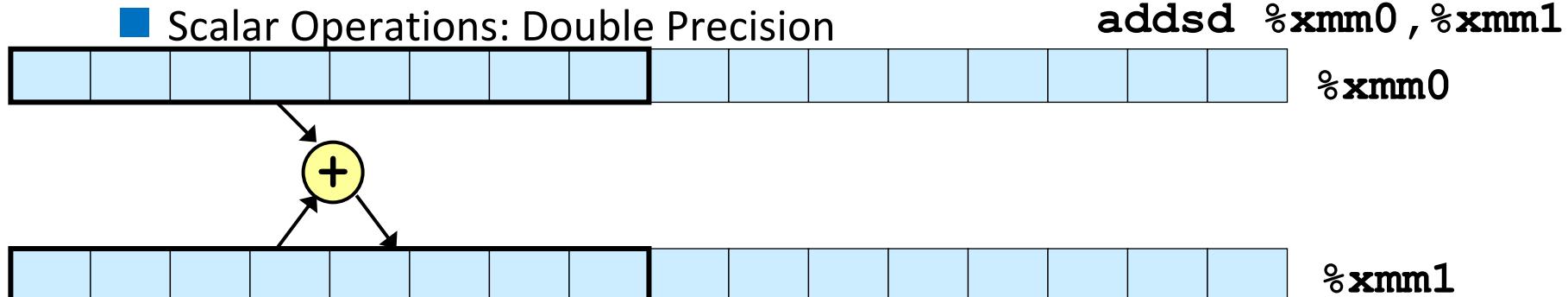
Scalar Operations: Single Precision



SIMD Operations: Single Precision



Scalar Operations: Double Precision



FP Basics

- Arguments passed in %xmm0, %xmm1, ...
- Result returned in %xmm0
- All XMM registers caller-saved

```
float fadd(float x, float y)
{
    return x + y;
}
```

```
double dadd(double x, double y)
{
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss    %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd    %xmm1, %xmm0
ret
```

FP Memory Referencing

- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd  %xmm0, %xmm1    # Copy v
movsd   (%rdi), %xmm0  # x = *p
addsd   %xmm0, %xmm1    # t = x + v
movsd   %xmm1, (%rdi)  # *p = t
ret
```

Other Aspects of FP Code

■ Lots of instructions

- Different operations, different formats, ...

■ Floating-point comparisons

- Instructions **ucomiss** and **ucomisd**
- Set condition codes ZF, PF and CF
- Zeros OF and SF

Parity Flag

UNORDERED: ZF,PF,CF ← **111**
GREATER_THAN: ZF,PF,CF ← **000**
LESS_THAN: ZF,PF,CF ← **001**
EQUAL: ZF,PF,CF ← **100**

■ Using constant values

- Set XMM0 register to 0 with instruction **xorpd %xmm0, %xmm0**
- Others loaded from memory

Summary

■ Arrays

- Elements packed into contiguous region of memory
- Use index arithmetic to locate individual elements

■ Structures

- Elements packed into single region of memory
- Access using offsets determined by compiler
- Possible require internal and external padding to ensure alignment

■ Combinations

- Can nest structure and array code arbitrarily

■ Floating Point

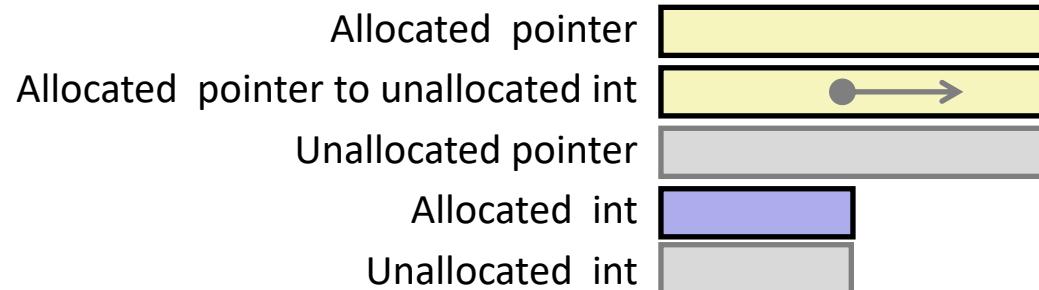
- Data held and operated on in XMM registers

Understanding Pointers & Arrays #3

Decl	<i>An</i>			<i>*An</i>			<i>**An</i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3][5]</code>									
<code>int *A2[3][5]</code>									
<code>int (*A3)[3][5]</code>									
<code>int *(A4[3][5])</code>									
<code>int (*A5[3])[5]</code>									

- **Cmp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by sizeof**

Decl	<i>***An</i>		
	Cmp	Bad	Size
<code>int A1[3][5]</code>			
<code>int *A2[3][5]</code>			
<code>int (*A3)[3][5]</code>			
<code>int *(A4[3][5])</code>			
<code>int (*A5[3])[5]</code>			



Declaration

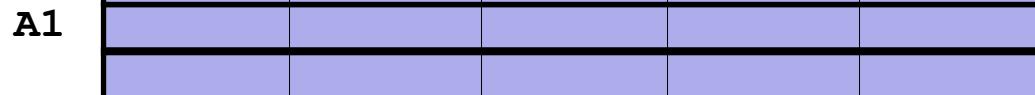
`int A1[3][5]`

`int *A2[3][5]`

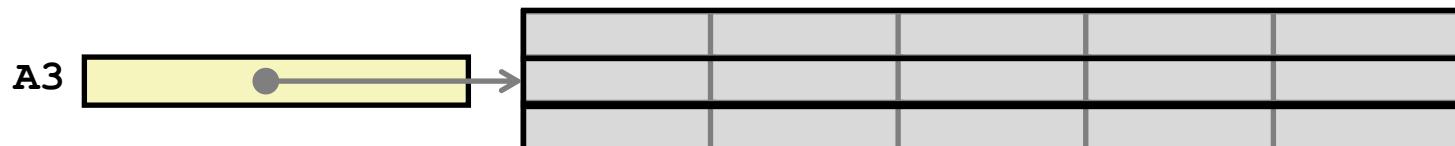
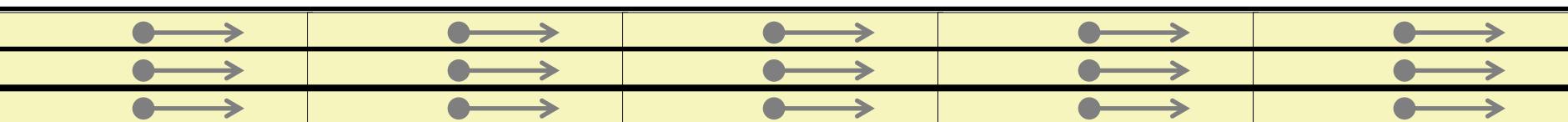
`int (*A3)[3][5]`

`int *(A4[3][5])`

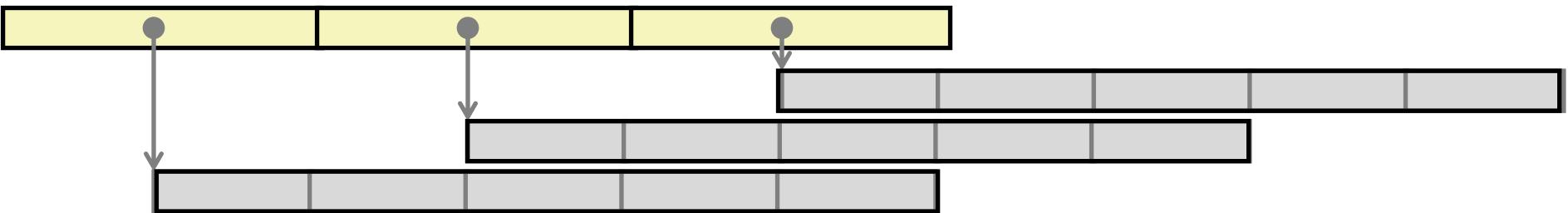
`int (*A5[3])[5]`



A2/A4



A5



Understanding Pointers & Arrays #3

Decl	<i>An</i>			<i>*An</i>			<i>**An</i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
int A1[3][5]	Y	N	60	Y	N	20	Y	N	4
int *A2[3][5]	Y	N	120	Y	N	40	Y	N	8
int (*A3)[3][5]	Y	N	8	Y	Y	60	Y	Y	20
int *(A4[3][5])	Y	N	120	Y	N	40	Y	N	8
int (*A5[3])[5]	Y	N	24	Y	N	8	Y	Y	20

- **Cmp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by sizeof**

Decl	<i>***An</i>		
	Cmp	Bad	Size
int A1[3][5]	N	-	-
int *A2[3][5]	Y	Y	4
int (*A3)[3][5]	Y	Y	4
int *(A4[3][5])	Y	Y	4
int (*A5[3])[5]	Y	Y	4